

# Cointegration Lecture III: Identifying the CVAR

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# Recap

Last week:

- Discussed *estimation* under the *reduced rank* hypothesis.
- Considered tests for *rank determination*.
- Briefly introduced tests to check for *parameter constancy*.

This week:

- Test (identifying) restrictions on *long-run structure* ( $\beta$ ).
- Test restrictions on the *adjustment structure* ( $\alpha$ ).
- Discuss *short-run structure* ( $p$  equations in differences).

# Outline

Restrictions on  $\beta$

Identification of long-run

Restrictions on  $\alpha$

Identification of short run

Appendix: Bivariate normal

## Testing restrictions

Consider simple model:

$$\underbrace{y_t}_{p \times 1} = \underbrace{\gamma'}_{p \times k} \underbrace{x_t}_{k \times 1} + \underbrace{\epsilon_t}_{p \times 1}$$

To test whether elements in  $\gamma$  are equal to zero, we write  $R'\gamma = 0$ , e.g. for  $k = 2$  and  $\mathcal{H}_0 : \gamma_1 = 0$ , we have  $R' = [1, 0]$ .

$$\underbrace{R'}_{m \times k} \gamma = 0 \quad \Leftrightarrow \quad \gamma = \underbrace{H}_{k \times (k-m)} \underbrace{\varphi}_{(k-m) \times p}, \quad H = R_{\perp}$$

So we can write

$$y_t = \varphi' H' x_t + \epsilon_t,$$

and the maximum likelihood estimator given assumed  $H$  becomes

$$\begin{aligned} \hat{\varphi}_{ML} &= (H' S_{xx} H)^{-1} H' S_{xy} \\ \hat{\gamma}_{ML} &= H \hat{\varphi}_{ML} = H (H' S_{xx} H)^{-1} H' S_{xy} \end{aligned}$$

Now use LR test to test  $\mathcal{H}_0 : \gamma = H\varphi$  against unrestricted model.

## Hypotheses on $\beta$

$$\Delta \mathbf{x}_t = \alpha \beta' \mathbf{x}_{t-1} + \varepsilon_t$$

Linear restrictions on cointegration space

$$\beta = \underbrace{H}_{p \times s} \underbrace{\varphi}_{s \times r} \Leftrightarrow R' \beta = 0,$$

where  $s = p - m$  and  $m$  is the number of restrictions imposed.

Some cointegrating vectors known

$$\beta = \left( \underbrace{b}_{p \times n}, \underbrace{H}_{p \times s} \underbrace{\varphi}_{s \times (r-n)} \right)$$

For these restrictions, the likelihood can be maximised analytically.

*Advantage:* uniqueness of maximum can be proved.

## Recall estimation of cointegrating vectors

$$\begin{aligned}
 L(\beta) &= \max_{\alpha, \Omega} L(\alpha, \beta, \Omega) = |\hat{\Omega}(\beta)|^{-T/2} \\
 &= \left[ |\mathbf{S}_{00}| \frac{|\beta'(\mathbf{S}_{11} - \mathbf{S}_{10}\mathbf{S}_{00}^{-1}\mathbf{S}_{01})\beta|}{|\beta'\mathbf{S}_{11}\beta|} \right]^{-T/2}.
 \end{aligned}$$

Solve  $|\lambda\mathbf{S}_{11} - \mathbf{S}_{10}\mathbf{S}_{00}^{-1}\mathbf{S}_{01}| = 0$  for eigenvalues

$1 \geq \hat{\lambda}_1 \geq \dots \geq \hat{\lambda}_p \geq 0$ , and eigenvectors  $\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_p$  such that

$$\hat{\lambda}_i \mathbf{S}_{11} \hat{\mathbf{v}}_i = \mathbf{S}_{10} \mathbf{S}_{00}^{-1} \mathbf{S}_{01} \hat{\mathbf{v}}_i, \quad \hat{\mathbf{v}}_i' \mathbf{S}_{11} \hat{\mathbf{v}}_i = 1, \quad \hat{\mathbf{v}}_i' \mathbf{S}_{11} \hat{\mathbf{v}}_j = 0 \text{ for } i \neq j.$$

$$\hat{\beta} = (\hat{\mathbf{v}}_1, \dots, \hat{\mathbf{v}}_r), \quad \max_{\alpha, \beta, \Omega} L(\alpha, \beta, \Omega) = \left[ |\mathbf{S}_{00}| \prod_{i=1}^r (1 - \hat{\lambda}_i) \right]^{-T/2}.$$

## Testing $\beta = H\varphi$

$$L(\varphi) = \left[ |\mathbf{S}_{00}| \frac{|\varphi' H' (\mathbf{S}_{11} - \mathbf{S}_{10} \mathbf{S}_{00}^{-1} \mathbf{S}_{01}) H \varphi|}{|\varphi' H \mathbf{S}_{11} H \varphi|} \right]^{-T/2}.$$

Solve  $|\lambda H' \mathbf{S}_{11} H - H' \mathbf{S}_{10} \mathbf{S}_{00}^{-1} \mathbf{S}_{01} H| = 0$  for eigenvalues  $1 \geq \lambda_1^* \geq \dots \geq \lambda_s^* \geq 0$ , and eigenvectors  $\mathbf{v}_1^*, \dots, \mathbf{v}_s^*$ . Then:

$$\hat{\varphi} = (\mathbf{v}_1^*, \dots, \mathbf{v}_r^*), \quad \max_{\alpha, \varphi, \Omega} L(\alpha, \varphi, \Omega) = \left[ |\mathbf{S}_{00}| \prod_{j=1}^r (1 - \lambda_j^*) \right]^{-T/2}.$$

*Likelihood ratio test statistic:*

$$LR(\beta = H\varphi | \mathcal{H}_r) = -T \sum_{j=1}^r \ln \left\{ \frac{(1 - \lambda_j^*)}{(1 - \hat{\lambda}_j)} \right\}.$$

# Asymptotic theory

## Theorem

### **Johansen, Theorems 7.2**

*Assumption 3.1 (A), (B), (C). Then*

$$LR(\beta = H\varphi | \mathcal{H}_r) \xrightarrow{D} \chi^2 \{r(p-s)\}$$

*Nielsen (2000): In Johansen's Theorem 7.2*

*(i) Assumption 3.1 (B), (C) are not necessary*

*(ii) However, distribution of LR (restriction on  $\beta$ ) does depend on  $r$ .*

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Restrictions on  $\beta$

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Appendix: Bivariate normal

## Identification of $\beta$

Cointegrating *vectors* not unique but cointegrating *space* unique.  
 For any invertible  $\xi \in \mathbf{R}^{r \times r}$  then

$$\alpha\beta' = \alpha\xi^{-1}\xi\beta'$$

$\Rightarrow$  Unrestricted estimation under reduced rank gives  
 $\text{span}(\beta) = \text{span}(\beta\xi')$  but not a unique  $\beta$ .

Since unrestricted estimation only gives us cointegration space, we need to impose individual restrictions on each  $\beta_i$  in order to gain meaningful economic insights:

$$\beta = \left( \underbrace{H_1}_{p \times s_1} \underbrace{\varphi_1}_{s_1 \times 1}, \dots, \underbrace{H_r}_{p \times s_r} \underbrace{\varphi_r}_{s_r \times 1} \right)$$

The likelihood needs to be maximised (locally?) by numerical procedures, e.g.

- “Switching algorithm”
- Newton-Raphson routines - as in PcGive.

A rank condition holds for an identified cointegrating relation:

$$\text{rank}(R'_1\beta_1, R'_1\beta_2, \dots, R'_1\beta_r) = \text{rank}(R'_1H_1\varphi_1, R'_1H_2\varphi_2, \dots, R'_1H_r\varphi_r) = r - 1$$

$\Rightarrow \beta_2, \beta_3, \dots, \beta_r$  can't be combined to form space spanned by  $\beta_1$ .  
 To check rank condition, need to know  $\beta_i = H_i\varphi_i$ , but to estimate coefficients, need to know whether restrictions are identifying... So check rank condition in terms of known  $H_i$ , e.g. for  $r = 2$ ,

$$\text{rank}(R'_iH_j) \geq r - 1 = 1, \quad i \neq j.$$

The equality holds for *just-identifying* restrictions and the inequality for *over-identifying* restrictions.

- Just-identified system: achieved by linear combination of the long-run equations, and hence does not alter likelihood function.
- Over-identified system: constrains parameter space through additional restrictions, and hence changes likelihood function. Use LR test to test restrictions. Need at least  $r$  restrictions on each equation.

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# Tests for hypotheses on $\alpha$ <sup>1</sup>

Linear restrictions on cointegration space

$$\alpha = \underbrace{A}_{p \times s} \underbrace{\psi}_{s \times r} \Leftrightarrow R' \alpha = 0$$

Testing a known vector in  $\alpha$

$$\alpha = \left( \underbrace{a}_{p \times n}, \underbrace{A}_{p \times s}, \underbrace{\psi}_{s \times (r-n)} \right)$$

Estimation linked with estimation of  $\beta$ !

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<sup>1</sup>see Doornik, Hendry and Nielsen (1998) and Johansen (1996), Ch. 8.

# Asymptotic theory

## Theorem

**Johansen, Theorem 8.2, 8.4.** *Assumptions A,B and C. Then*

$$LR(\text{restriction on } \alpha) \xrightarrow{D} \chi^2(n)$$

where

$$\begin{aligned} n &= (p - s)r && \text{for } \alpha = A\psi \\ n &= \#col(a) \times (p - r) && \text{for } \alpha = (a, A\psi) \end{aligned}$$

*Degrees of freedom are computed numerically.*

## Hypotheses on $\alpha$ and common trends<sup>2</sup>

If last row of  $\alpha$  is zero (and  $p - r = 1$ ),

$$\begin{pmatrix} *(p-1 \times r) \\ 0_{(1 \times r)} \end{pmatrix} \in \text{span}(\alpha) \Leftrightarrow \begin{pmatrix} 0_{(p-1 \times 1)} \\ 1_{(1 \times 1)} \end{pmatrix} \in \text{span}(\alpha_{\perp}),$$

innovations of last equation in system cumulate to common stochastic trend in Granger-Johansen representation:

$$\mathbf{x}_t \approx \underbrace{\beta_{\perp}(\alpha'_{\perp}\beta_{\perp})^{-1}\alpha'_{\perp}}_C \sum_{s=1}^t \varepsilon_s + \text{stationary process} + A.$$

Also no adjustment of last equation to deviation from long-run:

$$\Delta \mathbf{x}_t = \alpha \beta' \mathbf{x}_{t-1} + \Gamma \Delta \mathbf{x}_{t-1} + \varepsilon_t.$$

*Weak exogeneity:* The last variable is then “weakly exogenous for  $\beta$ ”.

<sup>2</sup>See Juselius (2006), Ch. 14.3.

## Weak exogeneity<sup>3</sup>

Suppose process  $X$  has two components  $Y$  and  $Z$ .

**Q:** Is it sufficient to look at conditional likelihood of  $Y$  given  $Z$ ?

Joint density satisfy

$$f_{\lambda, \phi}(y, z) = f_{\phi}(y|z) f_{\lambda}(z).$$

Partition likelihood as

$$L_{Y,Z}(\lambda, \phi) = L_{Y|Z}(\phi) L_Z(\lambda)$$

**Q:** is

$$\max_{\lambda, \phi} L_{Y,Z}(\lambda, \phi) = \left\{ \max_{\phi} L_{Y|Z}(\phi) \right\} \left\{ \max_{\lambda} L_Z(\lambda) \right\}?$$

*Sufficient condition:*  $\phi$  and  $\lambda$  vary freely.

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<sup>3</sup>Hendry (1995), Ch. 5.

Exogeneity condition applies to one observation

$$\max_{\lambda, \phi} L_{Y,Z}(\lambda, \phi) = \left\{ \max_{\phi} L_{Y|Z}(\phi) \right\} \left\{ \max_{\lambda} L_Z(\lambda) \right\}$$

Suppose  $X_1, \dots, X_T$  is time series with two components  $Y_t$  and  $Z_t$ .

$$\begin{aligned} L_{X_1, \dots, X_T}(\lambda, \phi) &= \prod_{t=1}^T L_{(X_t|past)}(\lambda, \phi) \\ &= \left\{ \prod_{t=1}^T L_{(Y_t|Z_t, past)}(\phi) \right\} \left\{ \prod_{t=1}^T L_{(Z_t|past)}(\lambda) \right\} \end{aligned}$$

## Definition

According to Engle, Hendry and Richard (1983),  $Z_t$  is **weakly exogenous** for  $\theta$  if

- (i)  $\lambda, \phi$  vary freely, and
- (ii)  $\theta$  is a function of  $\phi$  only.

## Weak exogeneity in cointegrated VAR<sup>4</sup>

*Joint* cointegrated VAR:

$$\begin{pmatrix} \Delta \mathbf{y}_t \\ \Delta \mathbf{z}_t \end{pmatrix} = \begin{pmatrix} \alpha_y \\ \alpha_z \end{pmatrix} \beta' \begin{pmatrix} \mathbf{y}_{t-1} \\ \mathbf{z}_{t-1} \end{pmatrix} + \begin{pmatrix} \varepsilon_{y,t} \\ \varepsilon_{z,t} \end{pmatrix}$$

*Conditional* model for  $\mathbf{y}_t$  given  $\mathbf{z}_t$  is, with  $\omega = \Omega_{yz}\Omega_{zz}^{-1}$ ,

$$\Delta \mathbf{y}_t = (\alpha_y - \omega \alpha_z) \beta' \mathbf{x}_{t-1} + \omega \Delta \mathbf{z}_t + (\varepsilon_{y,t} - \omega \varepsilon_{z,t})$$

*Marginal* model for  $\mathbf{z}_t$  is

$$\Delta \mathbf{z}_t = \alpha_z \beta' \mathbf{x}_{t-1} + \varepsilon_{z,t}.$$

- $\mathbf{z}_t$  is weakly exogenous for  $\beta$  ('long-run weakly exogenous') if  $\alpha_z = \mathbf{0}$ .

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<sup>4</sup>Juselius (2006), Ch. 11.

We then have parameter spaces

$$\begin{aligned}\lambda &= (\Omega_{zz}) \\ \phi &= (\alpha_y, \beta, \omega, \Omega_{yy} - \Omega_{yz}\Omega_{zz}^{-1}\Omega_{zy})\end{aligned}$$

For long-run weak exogeneity of  $\mathbf{z}_t$ , our parameter of interest is  $\beta$ -matrix. Is  $\alpha_z = 0$  sufficient for long-run weak exogeneity?

- (i) It can be shown that parameters in  $\lambda$  and  $\phi$  are variation free from each other, fulfilling condition (i).<sup>5</sup>
- (ii)  $\beta$  only enters parameter space  $\phi$ , so condition (ii) satisfied.

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<sup>5</sup>See Johansen (1996), Ch. 8.

## The partial model

Let  $\mathbf{x}_t = (\mathbf{y}_t, \mathbf{z}_t)'$ . If long-run weak exogeneity of  $\mathbf{z}_t$  with respect to  $\beta$  holds, we can analyse the conditional model of  $\mathbf{y}_t | \mathbf{z}_t$ , also called the partial model, on its own, and obtain a fully efficient estimate of  $\beta$ :

$$\Delta \mathbf{y}_t = \omega \Delta \mathbf{z}_t + \Gamma_{1,y} \Delta \mathbf{x}_{t-1} + \dots + \Gamma_{k-1,y} \Delta \mathbf{x}_{t-k+1} + \alpha_y \beta' \mathbf{x}_{t-1} + \mu_{0,y} + \varepsilon_{y,z,t}$$

Reasons to focus on the partial model:

- By conditioning on weakly exogenous variables, one can achieve a partial system with more stable parameters.
- Weak exogeneity may make sense *a priori*, e.g. it is unlikely that the Danish economy impacts on the US, but the US interest rate matters for the Danish economy.

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## Identification of the short-run structure<sup>6</sup>

Besides identifying the long-run structure, we can also restrict the short-run structure around lagged differences.

- We have  $p$  different equations in the system which determine the  $p$  current differences  $\Delta \mathbf{x}_t$  through lagged differences,  $r$  long-run relations and deterministic terms.
- Identification of the simultaneous short-run structure requires  $p - 1$  restrictions in each equation.
- If we have  $p_x$  weakly exogenous variables, we only need  $p - p_x - 1$  restrictions in each equation.
- Estimating the reduced form model

$$\mathbf{A}_0 \Delta \mathbf{x}_t = \mathbf{A}_0 \alpha \beta' \mathbf{x}_{t-1} + \mathbf{A}_0 \Gamma_1 \Delta \mathbf{x}_{t-1} + \mathbf{A}_0 \mu_0 + \mathbf{A}_0 \varepsilon_t,$$

where  $\mathbf{A}_0 = I$  imposes  $p - 1$  restrictions on each equation by definition, i.e. we have a just-identified system.

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<sup>6</sup>See Juselius (2006), Ch. 13.

## Structural models

If we are interested in a structural model where shocks can be given a structural interpretation, we need to find restrictions such that the residuals are uncorrelated, for example:

- Establish a causal chain among variables, i.e.  $\mathbf{A}_0$  becomes an upper triangular matrix, and restrict off-diagonal elements in the covariance matrix to zero.
- Orthogonalise the residuals directly, i.e. let  $\mathbf{A}_0 = \hat{\Omega}^{-1/2}$ .

## Summer school: The cointegrated VAR model

If you are planning to do empirical time series modelling either in your DPhil or in your job, I would recommend a summer school at the University of Copenhagen, entitled:

“Econometric Methodology and Macroeconomics Applications - the Cointegrated VAR Model”.

It is run by Søren Johansen, Katarina Juselius and Anders Rahbek and takes place from 4-24 August 2008. Besides technical lectures, you get the chance to work on your data set with the experts for three weeks – and have a paper written by the end of it!

For further information talk to me or visit  
[www.econ.ku.dk/Summerschool](http://www.econ.ku.dk/Summerschool).

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## The bivariate normal distribution

Suppose  $(Y_1, Z_1), \dots, (Y_n, Z_n)$  independent

$$\mathbf{N}_2 \left\{ \begin{pmatrix} \mu_y \\ \mu_z \end{pmatrix}, \begin{pmatrix} \Omega_{yy} & \Omega_{yz} \\ \Omega_{yz} & \Omega_{zz} \end{pmatrix} \right\}.$$

Let  $\omega = \Omega_{yx}\Omega_{xx}^{-1}$  be population regression coefficient. Then

$$\begin{pmatrix} 1 & -\omega \\ 0 & 1 \end{pmatrix} \begin{pmatrix} Y_i \\ Z_i \end{pmatrix} \stackrel{\text{D}}{=} \mathbf{N}_2 \left\{ \begin{pmatrix} \mu_y - \omega\mu_z \\ \mu_z \end{pmatrix}, \begin{pmatrix} \Omega_{yy} - \Omega_{yz}\Omega_{zz}^{-1}\Omega_{zy} & 0 \\ 0 & \Omega_{zz} \end{pmatrix} \right\}$$

so

$$(Y_i|Z_i) \stackrel{\text{D}}{=} \mathbf{N}(\mu_y + \omega(Z_i - \mu_z), \Omega_{yy} - \Omega_{yz}\Omega_{zz}^{-1}\Omega_{zy}), \quad Z_i \stackrel{\text{D}}{=} \mathbf{N}(\mu_z, \Omega_{zz})$$

# Exercises

1. Exam 2007, Question 6 (iii)-(vi).
2. Exam 2006, Question 5 (v), (vi).
3. Exam 2004, Question 8.
4. Exercise 5.3, Johansen (1996).
5. Exercise 5.6, Johansen (1996).

## References

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